



Optimal Control of Industrial Solvent-Based CO₂ Capture Plants

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Cybernetica at a glance

- Est. 2000, SINTEF spin-off
- Tailor-made model-based solutions
- Unique NMPC technology
 - Industrially proven
 - Increases profitability for our customers



Application areas

- Polymerization processes:
 - Phenolic resins, amino resins
 - PVC (S-PVC, Paste-PVC)
 - Emulsion polymerization
 - Polyolefins
- Metallurgical processes
 - Aluminum electrolysis
 - Silicon and ferrosilicon
 - Ferromanganese refining
 - Steel refining
 - Extrusion
- Energy and CCUS
 - Offshore production
 - Onshore processing plants
 - **CO₂ capture**



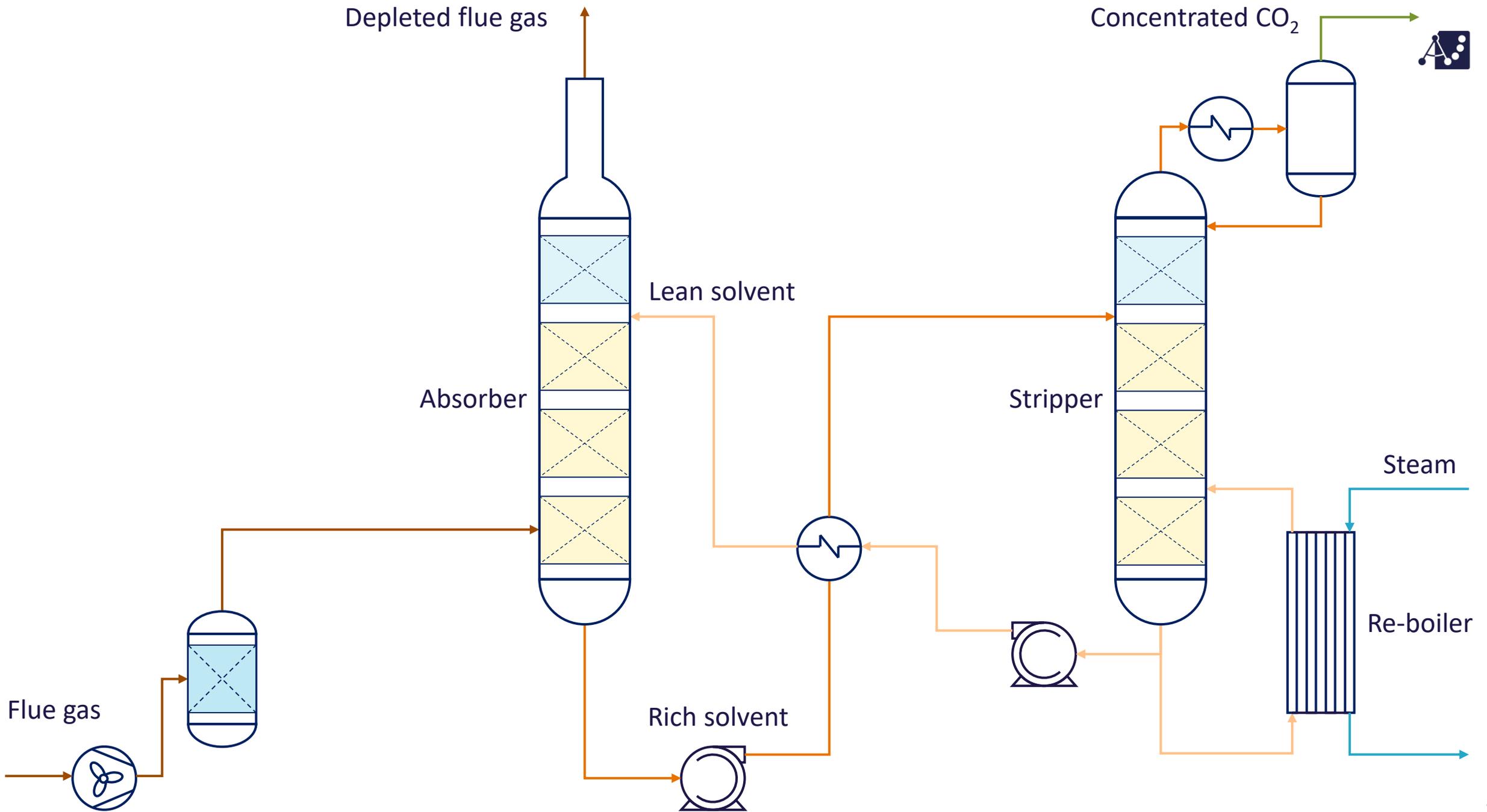
POLYMER



METALLURGICAL



ENERGY



Depleted flue gas

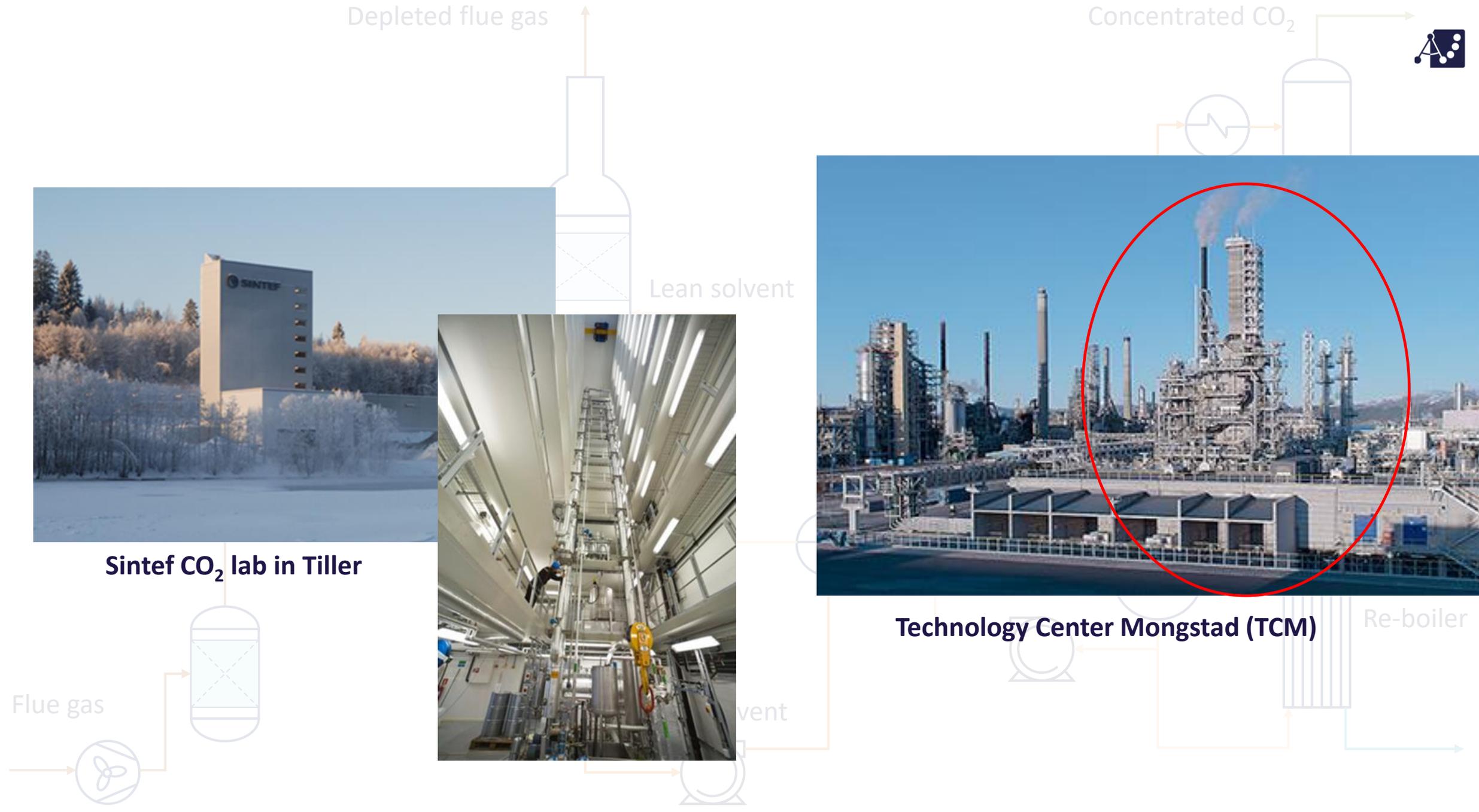
Concentrated CO₂

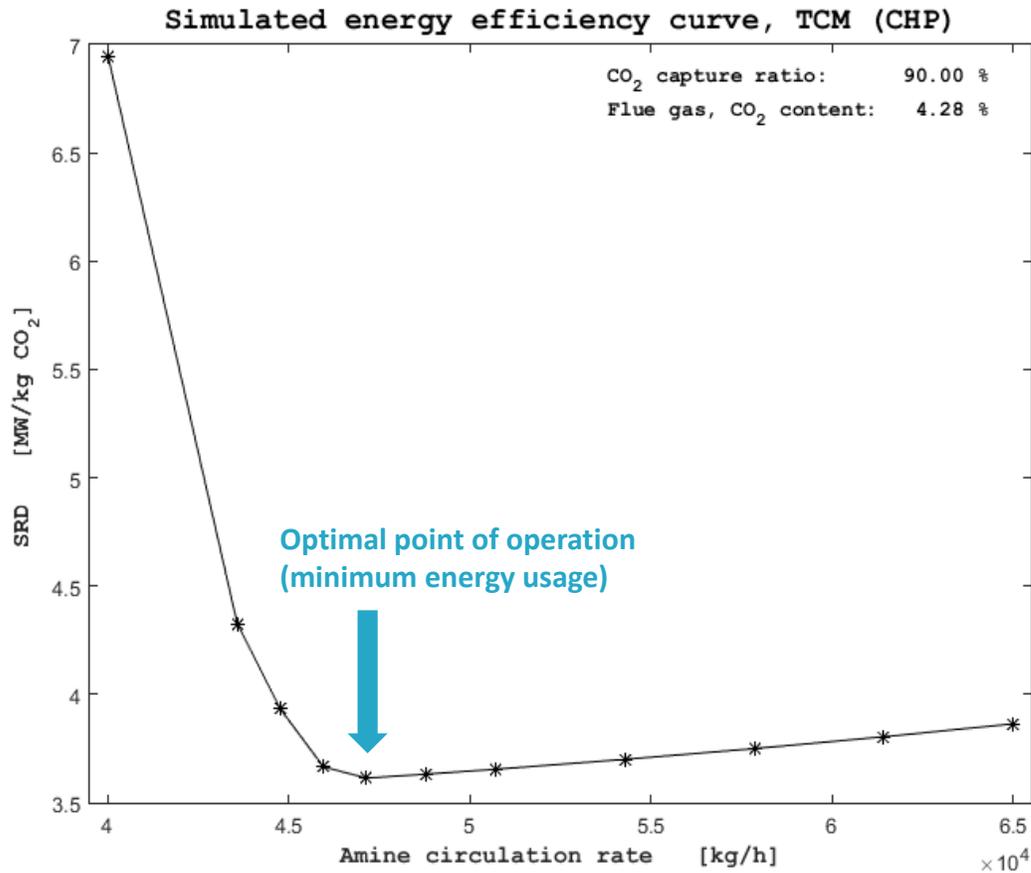


Sintef CO₂ lab in Tiller

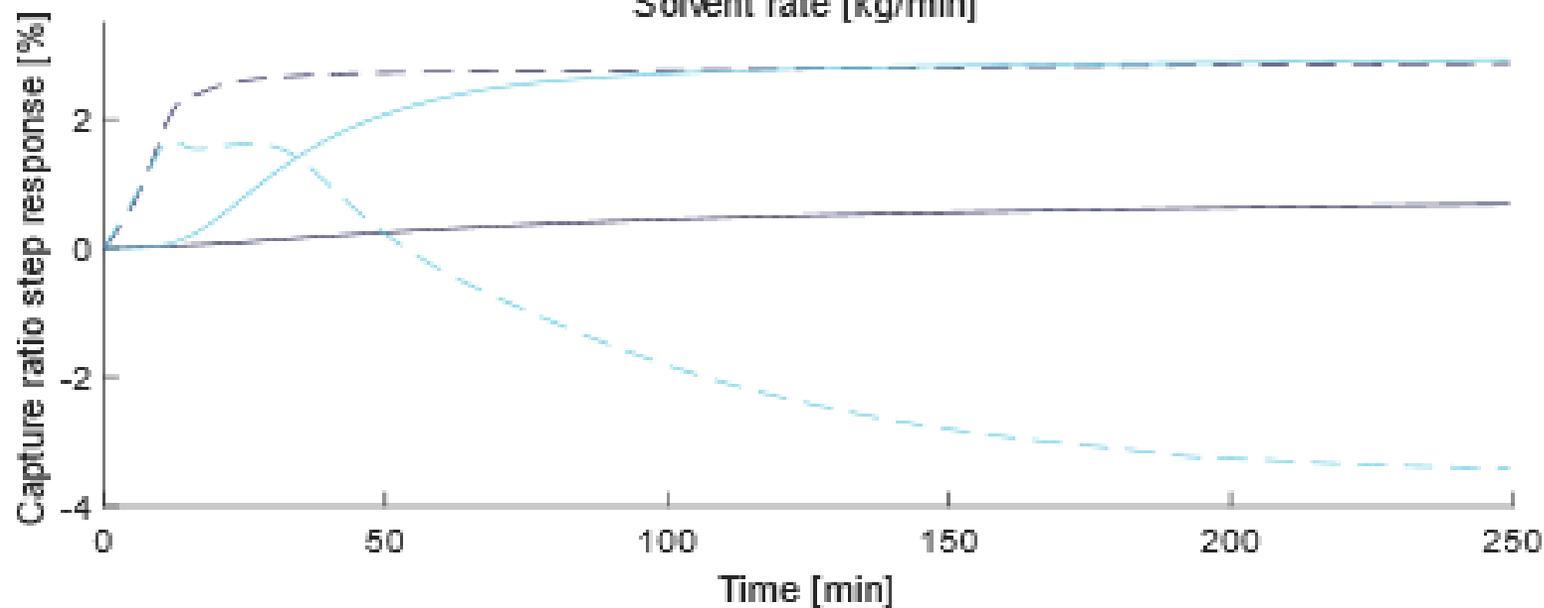
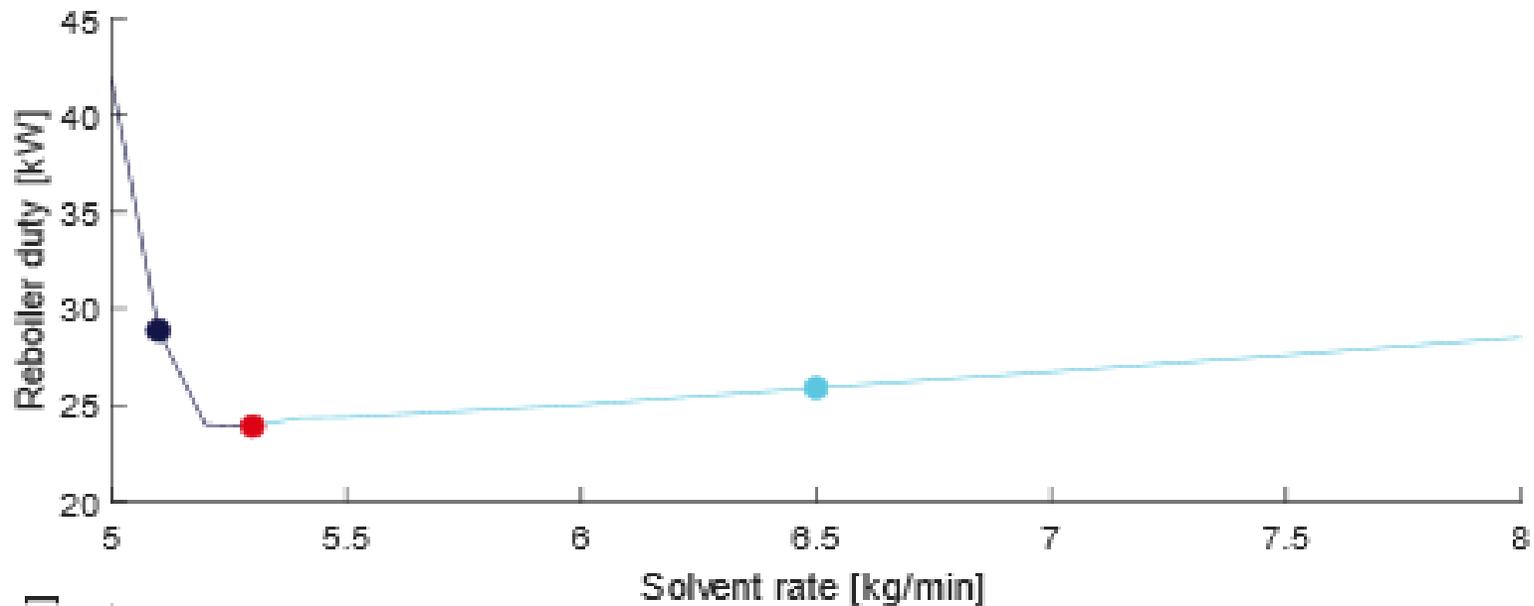


Technology Center Mongstad (TCM)





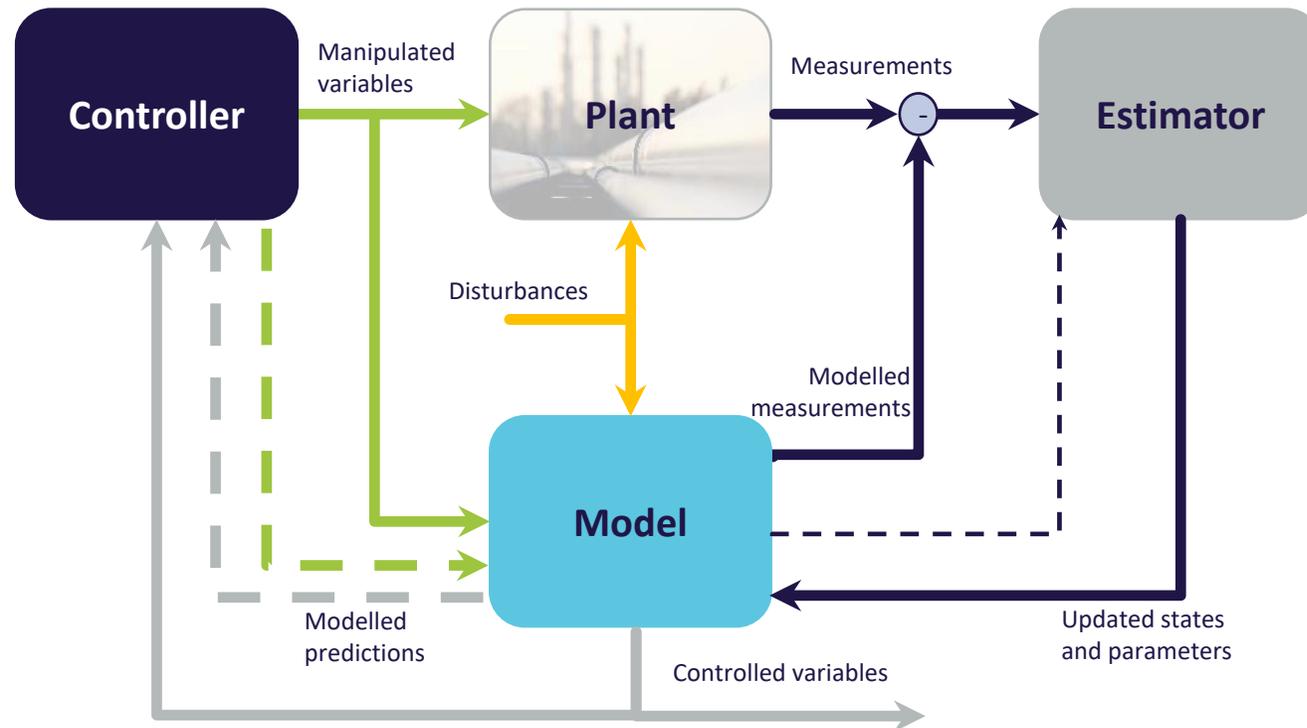
- A solvent-based CO₂ capture is a complex, nonlinear process with both fast and slow dynamics
- Optimal conditions change with
 - desired capture ratio
 - solvent concentration and degree of degradation
 - flue gas flow rate
 - flue gas composition



Controlling the process optimally will be hard using traditional (PID) control!



Model-based Predictive Control





Mathematical description

$$\min_{\Delta \mathbf{U}} J = \frac{1}{2} (\mathbf{Z} - \mathbf{Z}_{\text{ref}})^T \mathbf{Q} (\mathbf{Z} - \mathbf{Z}_{\text{ref}}) + \frac{1}{2} (\Delta \mathbf{U}^T \mathbf{S} \Delta \mathbf{U}) + \mathbf{r}_1^T \boldsymbol{\varepsilon} + \frac{1}{2} \boldsymbol{\varepsilon}^T \text{diag}(\mathbf{r}_2) \boldsymbol{\varepsilon}$$

Subject to

$$\mathbf{x}_{k+j} = \mathbf{f}(\mathbf{x}_{k+j-1}, \mathbf{u}_{k+j-1}, \mathbf{v}_k)$$

$$\mathbf{z}_{k+j} = \mathbf{h}(\mathbf{x}_{k+j}, \mathbf{u}_{k+j})$$

$$\mathbf{Z}_{\min} - \boldsymbol{\varepsilon} < \mathbf{Z} < \mathbf{Z}_{\max} + \boldsymbol{\varepsilon}$$

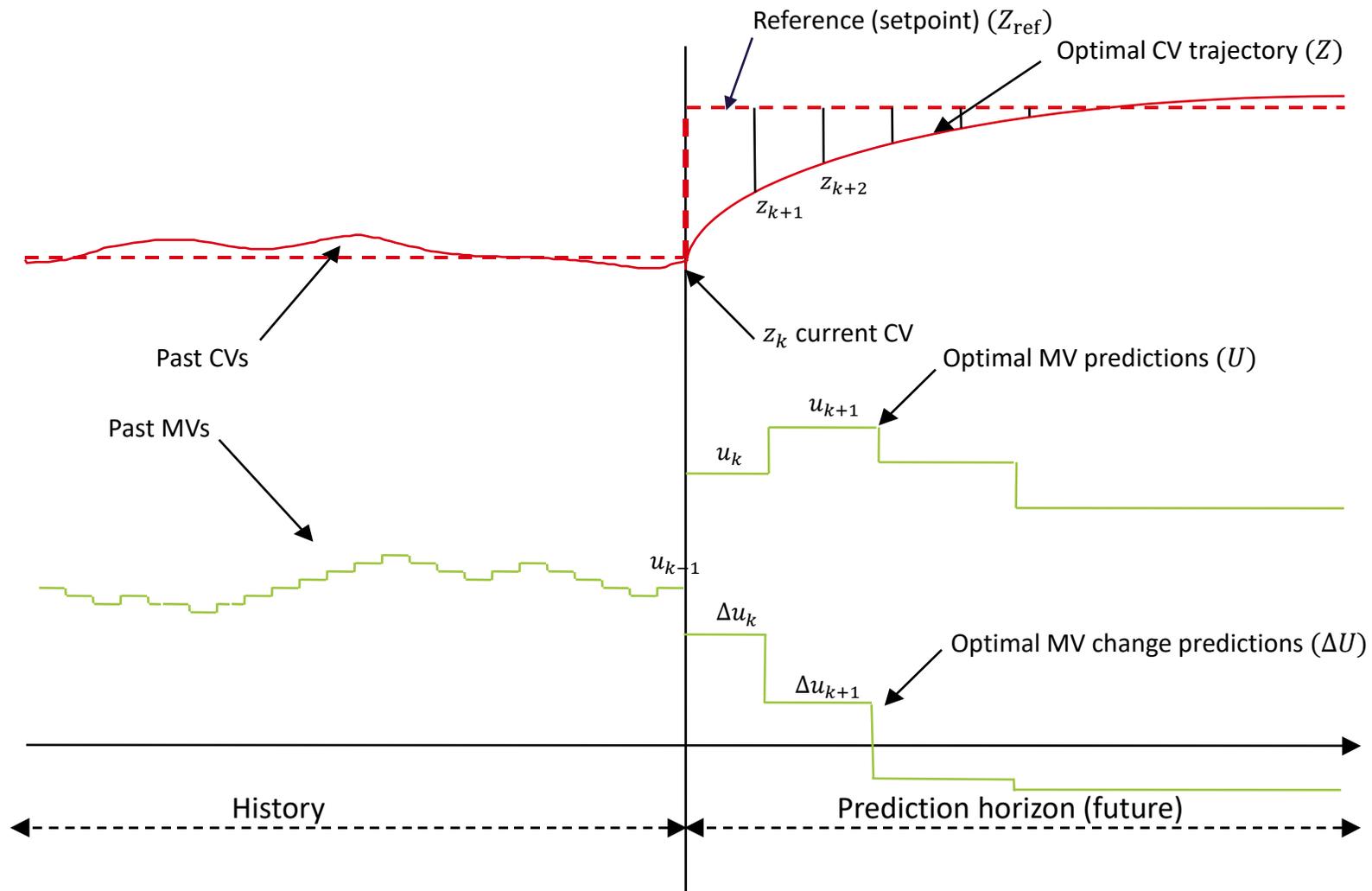
$$\mathbf{0} \leq \boldsymbol{\varepsilon} \leq \boldsymbol{\varepsilon}_{\max}$$

$$\mathbf{U}_{\min} \leq \mathbf{U} \leq \mathbf{U}_{\max}$$

$$\Delta \mathbf{U}_{\min} \leq \Delta \mathbf{U} \leq \Delta \mathbf{U}_{\max}$$



NMPC – Simplified graphical description





Augmented Extended Kalman Filter

- Augmented state vector
- Parameters modelled as integrated white noise
- Process noise covariance (\mathbf{V}_{k-1}) also defined for the parameters

Model prediction

$$\bar{\mathbf{x}}_k = \mathbf{f}(\hat{\mathbf{x}}_{k-1}, \hat{\boldsymbol{\theta}}_{k-1}, \mathbf{u}_{k-1}, \bar{\mathbf{v}}_{k-1})$$

$$\bar{\boldsymbol{\theta}}_k = \hat{\boldsymbol{\theta}}_{k-1} + \bar{\mathbf{v}}_{k-1}$$

$$\bar{\mathbf{y}}_k = \mathbf{g}(\bar{\mathbf{x}}_k, \hat{\boldsymbol{\theta}}_k, \mathbf{u}_{k-1}) + \bar{\mathbf{w}}_k$$

Measurement correction

$$\begin{bmatrix} \hat{\mathbf{x}}_k \\ \hat{\boldsymbol{\theta}}_k \end{bmatrix} = \begin{bmatrix} \bar{\mathbf{x}}_k \\ \bar{\boldsymbol{\theta}}_k \end{bmatrix} + \mathbf{K}(k)(\mathbf{y}_{M,k} - \bar{\mathbf{y}}_k)$$

CV1: Absorber capture rate (CR) – **Target**

$$CR = \frac{\dot{W}_{CO_2,in} - \dot{W}_{CO_2,abs.out}}{\dot{W}_{CO_2,in}}$$

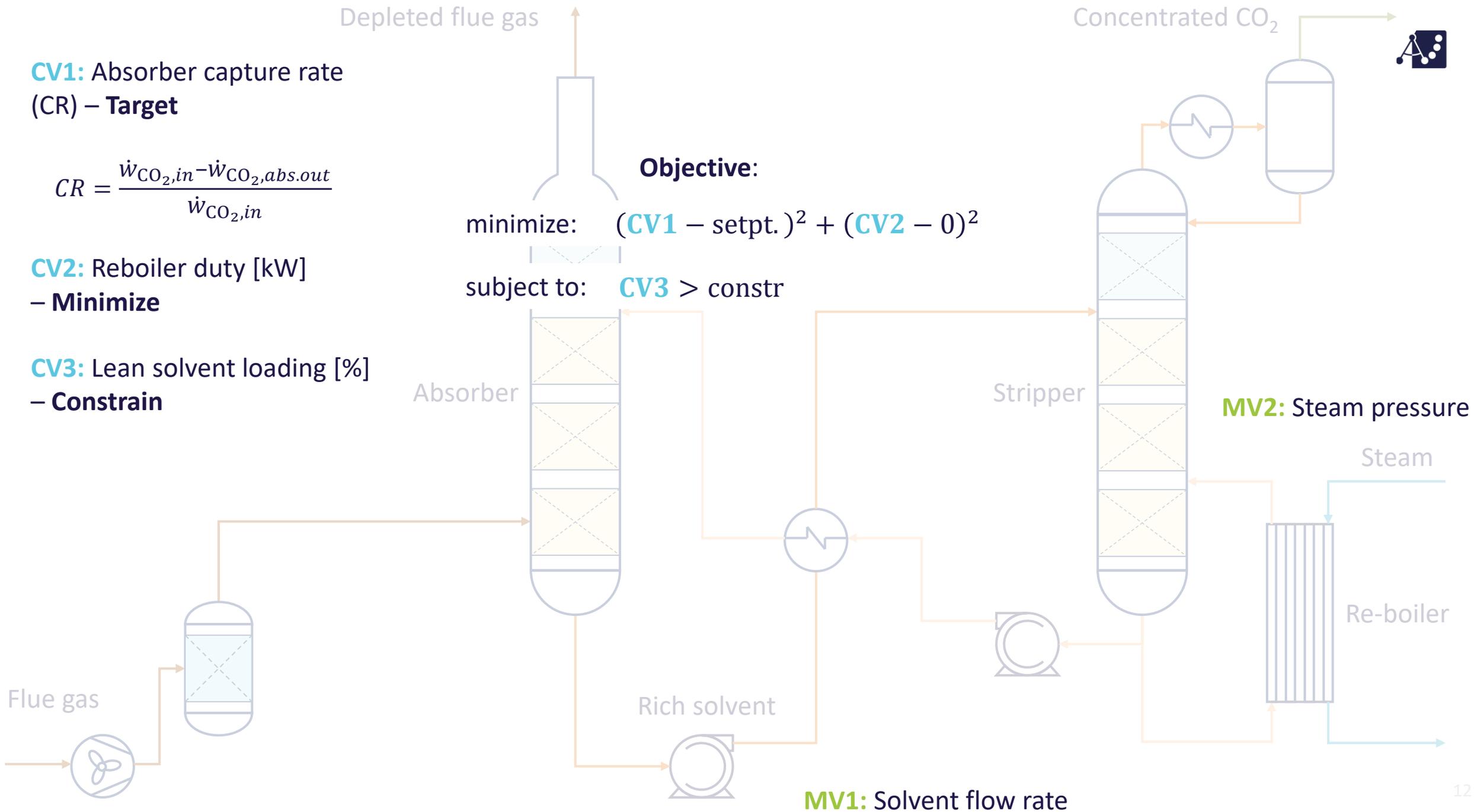
CV2: Reboiler duty [kW] – **Minimize**

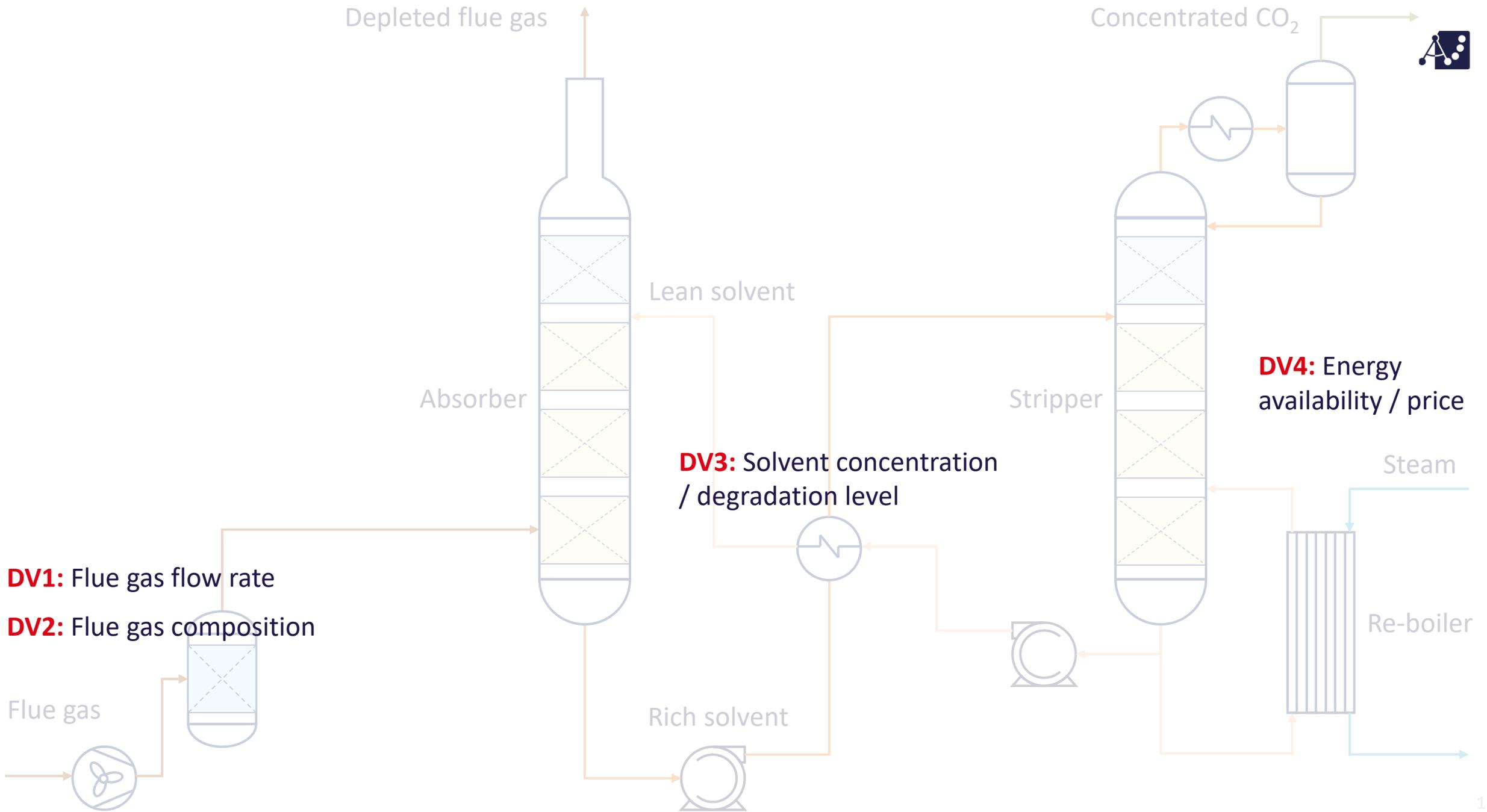
CV3: Lean solvent loading [%] – **Constrain**

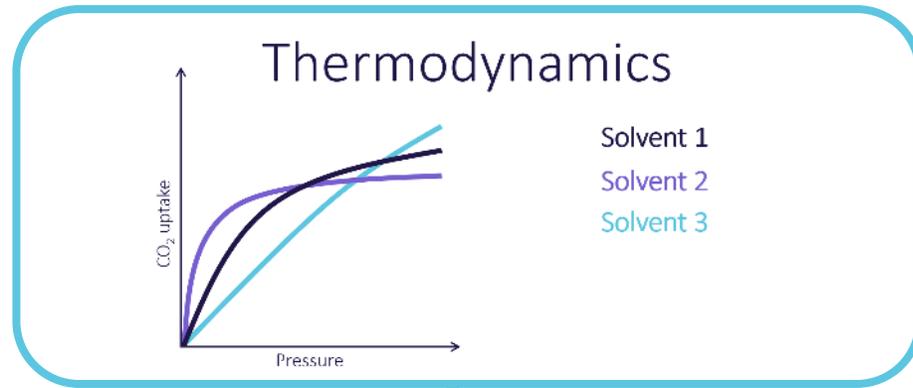
Objective:

minimize: $(CV1 - \text{setpt.})^2 + (CV2 - 0)^2$

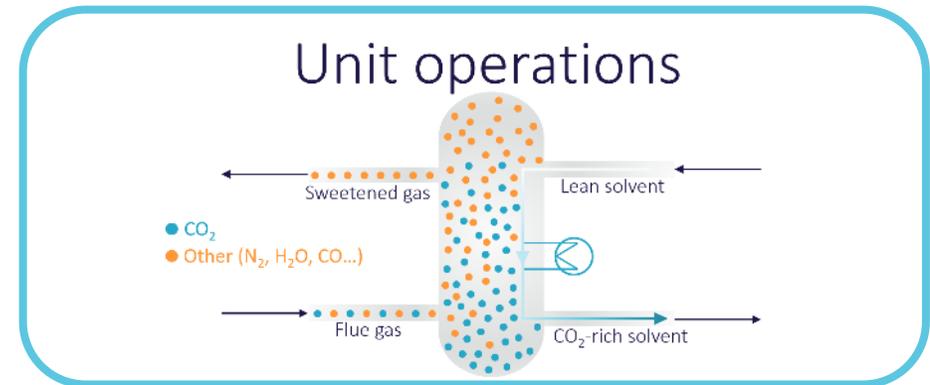
subject to: $CV3 > \text{constr}$







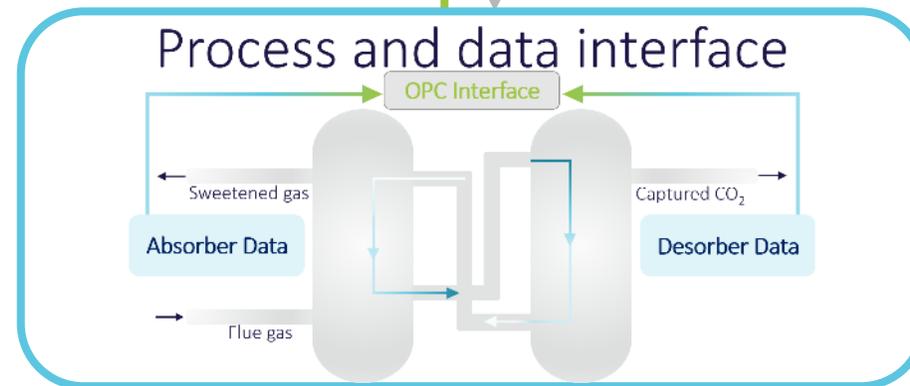
(Solvent-specific code)



(Common, generic code)

CENIT PCC model

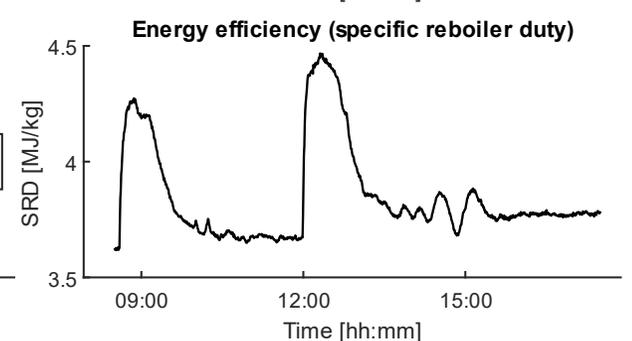
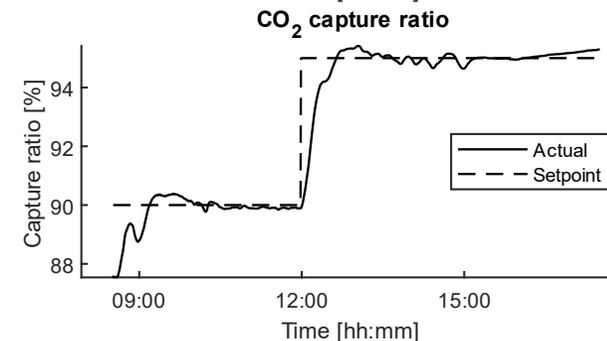
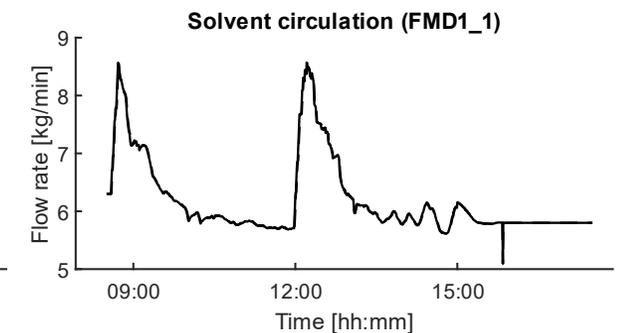
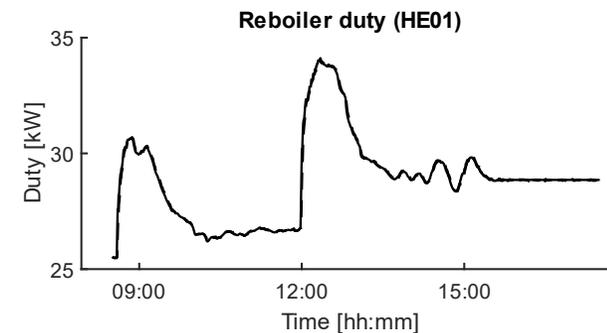
(Plant-specific code)





Capture rate, setpoint changes

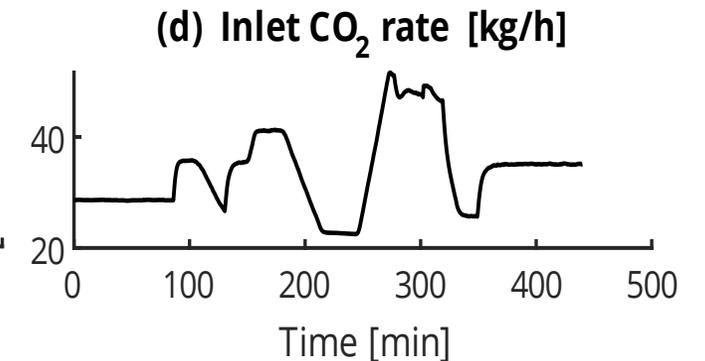
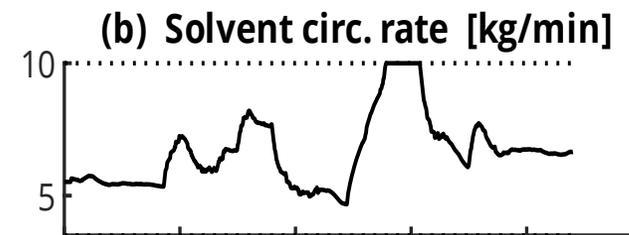
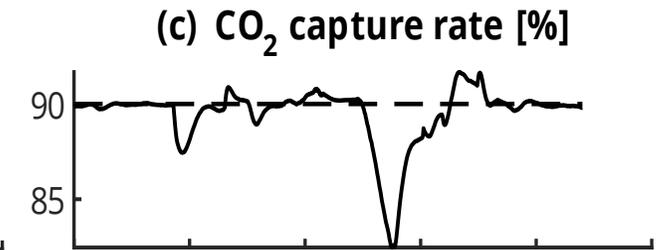
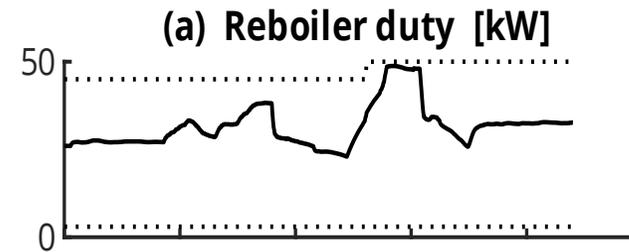
- Step in capture ratio setpoint
- Controller responds quickly
 - Obeys capture rate setpoint
 - Approaches the point of energy-optimal operation





Disturbance rejection

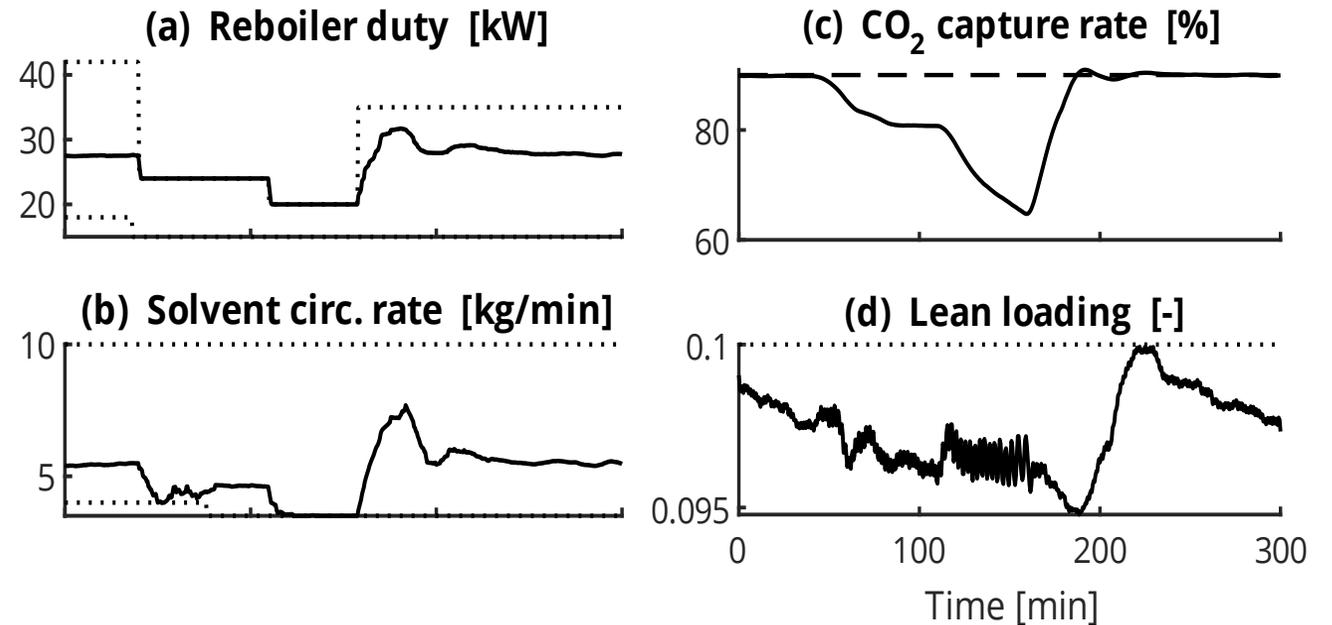
- Changing flue gas conditions
 - Flue gas CO₂ concentration
 - Flue gas inlet flow rate
- Rapid controller response
 - Stays at the prescribed capture rate, while minimizing reboiler duty





Special control cases: Energy availability

- Reboiler duty constraint tests
- Lean loading constraint
 - The controller will prioritize to maintain the loading rather than obeying the instantaneous capture rate setpoint





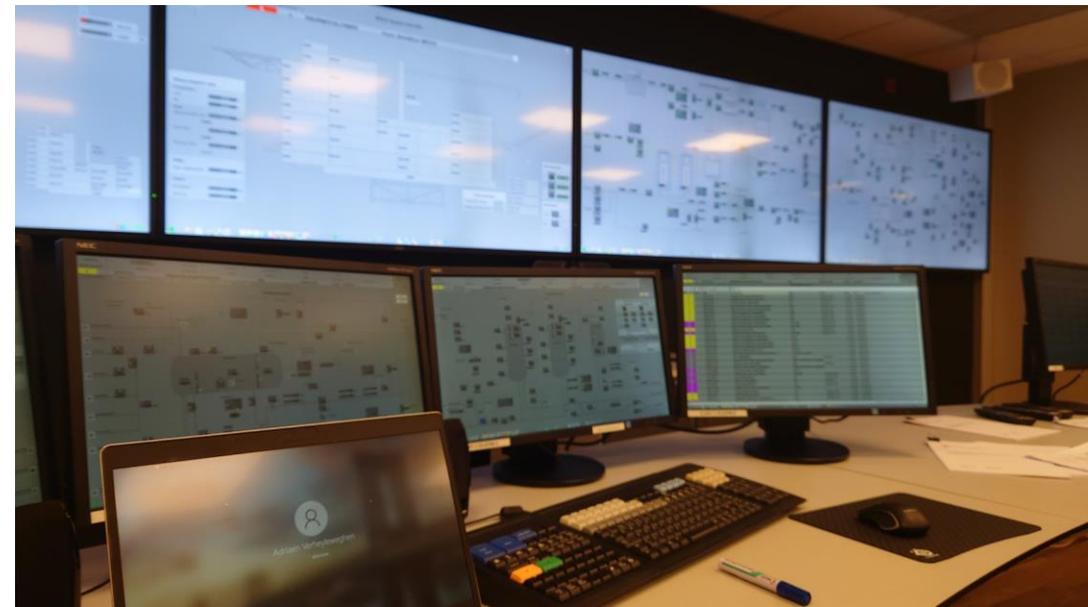
Special control cases: Economic optimization

- Day-to-day (24h) cost optimization, using DRTO
- Varying energy price
 - Energy cost savings in the range of 12%¹
- Flexible operation using storage tanks
 - Energy cost savings in the range of 33%¹

¹ For a proposed price regime

Implementation

- Close dialogue with end-user (production engineers & control room operators)
- Close cooperation with DCS supplier
- FAT / SAT on “digital twin” (high fidelity simulator for operator training)
- Remote monitoring of application during commissioning phase

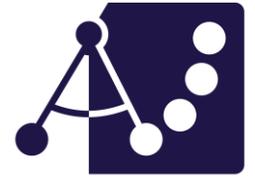




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Scientific papers

- S. O. Hauger, N. E. Flø, H. M. Kvamsdal, F. Gjertsen, T. Mejdell, M. Hillestad:
Demonstration of non-linear control of post-combustion CO₂ capture processes,
Computers and Chemical Engineering 123 (2019) 184-195
- H. M. Kvamsdal, S.O. Hauger, F. Gjertsen, N.E. Flø, K.E. Colombo, T. Mejdell, M. Hillestad:
Demonstration of two-level nonlinear model predictive control of CO₂ capture plants,
14th International Conference on Greenhouse Gas Control Technologies, GHGT-14, 21st – 25th October 2018, Melbourne, Australia.
- T. Mejdell, H. M. Kvamsdal, S. O. Hauger, F. Gjertsen, F. A. Tobiesen, M. Hillestad:
Demonstration of non-linear model predictive control for optimal flexible operation of a CO₂ capture plant, **International Journal of Greenhouse Gas Control 117 (2022) 103645, 2022.**
- F. Gjertsen, A. Verheyleweghen, S. O. Hauger, V. Tjessem, T. Mejdell, H. M. Kvamsdal:
Optimal Control of Industrial Solvent-Based CO₂ Capture Plants, **Computer Aided Process Engineering / 15th International Symposium on Process Systems Engineering (ESCAPE34/PSE24), 2024.**